

The geomagnetic field and TEC anomalies connected with the strong earthquakes

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A lot of scientific articles study correlation of seismic activity with variations of different components of the Earth's magnetic field. More often this is correlation with a single factor, such as secular variations, Sq-variations, Wolf's numbers, Kp- and Ap- indices, as well as with the frequency and origin times of geomagnetic storms, etc. However, this analysis does not give a complete pattern of the Earth's crust processes. To select and estimate the contribution of planetary geomagnetic processes and local responses and calculate the ratio of the external field T_e and telluric variations δT_i , we have to use data of remote and local stations[]. Moreover, the *ionosphere* conditions such as the total electron content (TEC), wind's velocity, the conductivity and current's density play the role.

At present, when the network of permanent dual-frequency receivers of the navigation system GPS ($f_1 = 1575.42$ MHz and $f_2 = 1227.60$ MHz) is widely spread, monitoring of the total electron content became much easier. The method of calculating TEC [2] is based on the dependence of the refractive index (n) of electromagnetic waves from the free electron concentration (N_e) and the wave frequency (f):

$$n = \sqrt{1 - 80.8 N_e / f^2} \approx 1 - 40.308 N_e / f^2.$$

The measured ways at the frequencies f_1 and f_2 are $S_1 = n_1 S_0 \approx (1 - 40.308 N_e / f_1^2) * S_0$ and $S_2 = n_2 S_0 \approx (1 - 40.308 N_e / f_2^2) * S_0$, respectively, where S_0 - a true satellite-receiver distance. Excluding the S_0 and integrating, we find the total electron content TEC_0 :

$$TEC_0 = \frac{1}{40.308} \frac{f_1^2 f_2^2}{f_1^2 - f_2^2} (L_1 * \lambda_1 - L_2 * \lambda_2 + S_{const} + \delta S),$$

where L_1 and L_2 - the numbers of complete turns of phase, λ_1 and λ_2 - the wavelengths (m) for frequencies f_1 and f_2 , S_{const} - some unknown initial phase ways (m) and δS - error in determining the phase ways (m). To determine S_{const} , which is the same as phase ambiguity resolution, code measurements P_1 and P_2 are used: $\delta S = \delta S_1 + \delta S_2 = (P_1 - L_1 \lambda_1) - (P_2 - L_2 \lambda_2) = (P_1 - P_2) - (L_1 \lambda_1 - L_2 \lambda_2)$. Taking into account the ballistics of the navigation satellite, we obtain:

$$TEC = TEC_0 * \cos[\arcsin(R_z \cos \theta / (R_z + h_{max}))],$$

where R_z - Earth's radius, h_{max} - the height of maximum electron density, θ - the height of satellite

visibility. To construct a continuous series variations of TEC with the least noise (because of the satellite's location near the horizon), we used only observations with θ equal to 57° – 90° .

The investigation of this series allows to detect seismic-ionospheric disturbances before and after strong earthquakes [3,4]. Fig. 1a shows the variations of TEC after the Nura's earthquake, $K = 13.25$ ($M_l = 6.6$), which occurred at 15 hours 52 minutes 5 October 2008, the epicenter's latitude is 39.62° N, longitude is 73.67° E. The level of geomagnetic disturbance was weak: $K_p = 1$. There is a sharp increase the amplitude of variations in 5-10 minutes on the nearest (126.5 km) to the epicenter GPS-station OSHK (40.53° N, 72.78° E), after ~ 1 hour oscillations are damped. On the other (more distant) stations such variations are not observed, that indicates the seismo-ionospheric character.

Using data from several GPS-receivers we can determine the velocity of the ionospheric disturbance (ID), and in a combination with the observations of the geomagnetic field T - to calculate the density the ionospheric current and the conductivity of the ionosphere. Suppose that receivers are located at a distance R from each other, and the time between the observations of ionospheric disturbances is Δt . The distance traveled by ID in the ionosphere is equal $R_{ion} \approx R \cdot (h_{orb} - h_{max}) / h_{orb}$, where the h_{orb} – height of the satellite's orbit, h_{max} – the height of maximum electron density. Taking the average values $h_{orb} = 20000$ km, $h_{max} = 300$ km, we have $R_{ion} \approx 0.985R$. Then the velocity of the ID is $v \approx 0.985R / \Delta t$.

The movement of electrons causes the electric current density $j = \sigma E$ [5], where σ is conductivity (also depends on the TEC) and $E = \mu_0 [v \cdot H]$ – the intensity of the electric field. The magnetic field is formed by the homogeneous current sheet of density j , must have a value of $\delta H = j/2$. Taking into account that the observed field by applying a field-induced currents about 1.5 times greater than the external, then the observed field is $\delta H = 3j/2$. Therefore, the conductivity of the ionosphere may be calculated as $\sigma = 2\delta H / 3\mu_0 [vH]$.

For example, consider the calculation conductivity of the ionosphere for GPS-stations POL2 (42.68° N, 74.69° E) and CHUM (42.99° N, 74.75° E). The variation of TEC and the full vector of the geomagnetic field T are shown in Fig. 1b, long-period trends have been removed. The variations of TEC_{POL2} and TEC_{CHUM} diverge and the time delay Δt is change in time. For t_A and t_B $\Delta t = 5.5$ min, $R = 35.7216$ km, then $v \approx 0.985R / \Delta t \approx 106.623$ m/s. The observed variation of the geomagnetic field is equal $\delta H = 6$ nT, $H = 40$ A/m, then $\sigma \approx 120$ S/m.

Thus, the complex analysis of the total variations of the geomagnetic field T and TEC allows to calculate the parameters of ionospheric disturbances and currents, and can be used to more effectively searching ionospheric oscillations associated with the strong earthquakes.

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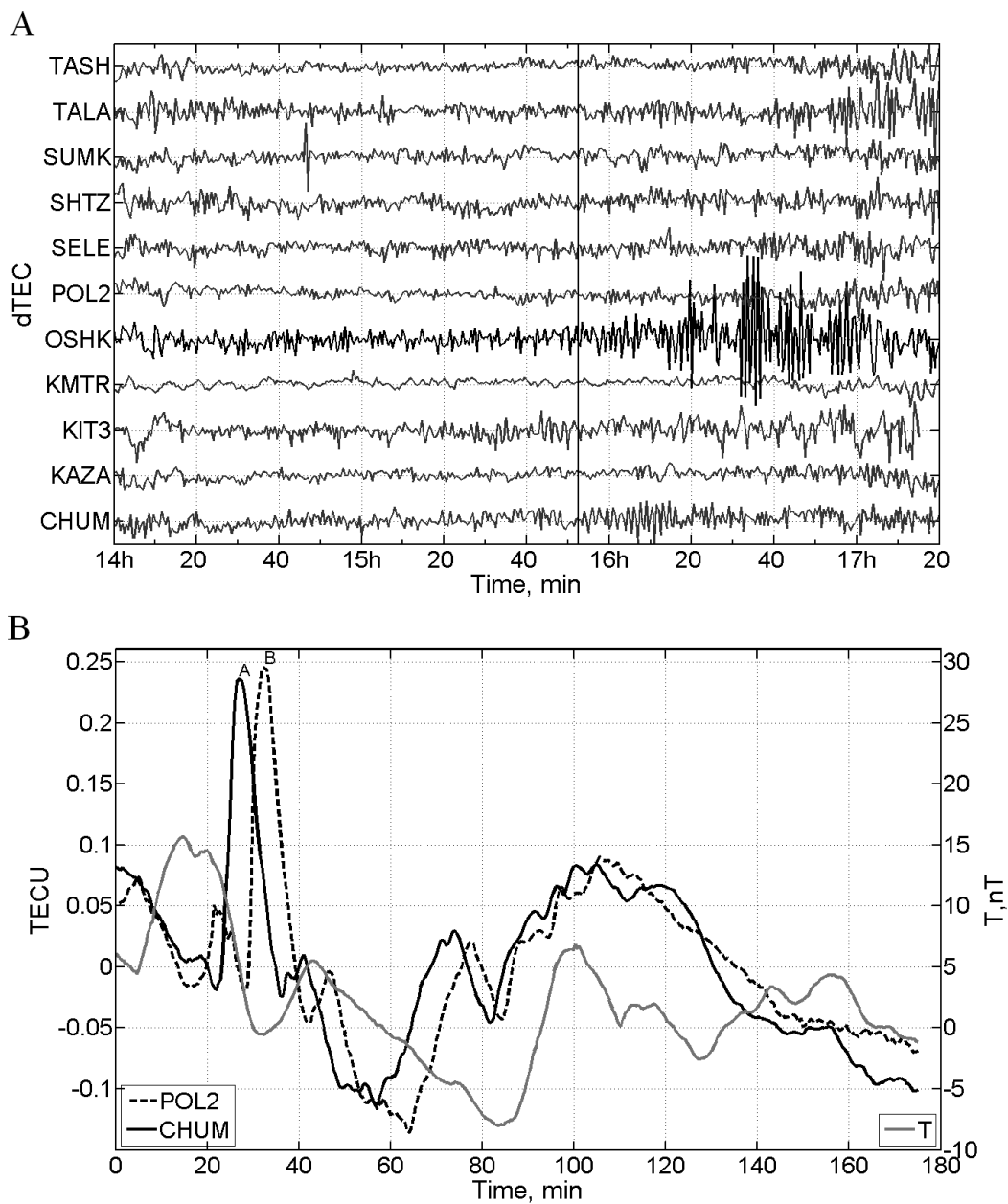


Fig. 1a: Variations dTEC during the Nura earthquake.

Fig. 1b: Variations TEC and the total vector of the geomagnetic field T.